Josep Maria Barbera

\$\(\big(+34 \) 644 496 426 | \(\subseteq \) josep.barbera@csic.es | \(\O \) jbarciv | in josep-barbera

My research is centered on autonomous vehicles, with a specific focus on trajectory generation and decision-making in driving scenarios. Additionally, I am exploring related topics such **ODD-aware** and reinforcement learning.

Education

PhD in Robotics: Autonomous Driving

CENTER FOR AUTOMATION AND ROBOTICS (CSIC-UPM) Autopia Program. Advisor: Jorge Villagra.

M.S. in Robotics Madrid, Spain

TECHNICAL UNIVERSITY OF MADRID · GPA: 9.16/10. 13 COURSES WITH A+ OR A. Advisor: Antonio Barrientos.

B.S. in Industrial Engineering. Major in Robotics and Electronics

TECHNICAL UNIVERSITY OF MADRID · GPA: 7.3/10. 6 COURSES WITH A+ OR A. Advisor: Damien Tourret

Experience _____

Technical University of Madrid - CEI RESEARCH INTERNSHIP

• Enhanced Neuroevolutionary Algorithms with GPU-based parallelization

- · Configured a GPU microserver with 2 NVIDIA A30 GPUs and 24 CPUs, and implemented CPU-GPU acceleration using Multi-Instance GPU (MIG) and Python's multiprocessing library
- Prepared a poster for the XV CEI Annual Meeting. [pdf]

Technical University of Madrid - Manufacturing Engineering Group

Certified Laboratory Practice Monitor

• Served laboratory practicals in the Manufacturing Automation and Robotics course

- · Prepared equipment, ensured safety measures, and drafted practice scripts and rules for tool usage
- Clarified doubts and maintained student commitment to completing laboratory tasks

IMDEA Materials Institute

Jun. 2022 - Oct. 2022

RESEARCH INITATION FELLOWSHIP

- · Contributed to research on computational oscillatory growth instability in directional solidifications Characterized oscillations and identified their occurrence conditions through computational modeling and DNN simulations (C++/Cuda, analyzed with Python)
- · Launched GPU cluster simulations and post-processed data for quantitative analysis using Jupyter Notebooks

Publications

Conference: On the Occurrence of Buoyancy-Induced Oscillatory Growth Instability During Directional Solidification of Alloys

2023 MODELLING OF CASTING, WELDING AND ADVANCED SOLIDIFICATION PROCESSES - XVI CONFERENCE

J. M. Barbera, Thomas Isensee, Damien Tourret

M.S. Thesis: Advanced Locomotion for Quadruped Robots Through **Reinforcement Learning**

J. M. Barbera

B.S. Thesis: Computational Study of Oscillatory Growth Instability in Directional Solidification of Alloys

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[pdf]

Arganda del Rey, Spain

2024 - Present

2023 - 2024

Madrid, Spain

2017 - 2023

Madrid

Madrid

Feb. 2023 - Aug. 2023

Feb. 2023 - May 2023

Getafe, Madrid

[pdf, code]

[pdf, code]

Projects _____

Master [code]

ROBOTICS Sept 2023 - Sept 2023 - Sept 2024

- Robotic Navigation Strategies for a Nocturnal Surveillance Application [code]
- A **Drowsiness Driving Alert** implementation with the use of MediaPipe [code]
- Exploring Urban and Natural Dynamics with **k-Means Clustering** [code]
- Bilateral Control with Wave Variables using Matlab [pdf]

Bachelor

ELECTRONICS AND AUTOMATION

Sept 2020 - Sept 2023

- Building a **SCARA robot** [pdf]
- FPGA programming with VHDL [code]
- Automatic Car Wash Programming in Microchip Studio [code]
- C++ object list to manage an Asteroids-style game by using the OpenGL cross-platform graphics library. [code]
- Dynamic Backtracking Maze Generator with a ramdomized version of the depth-first search algorithm. [code]

Languages ______

Spanish NativeCatalan NativeEnglish Proficient

[certificate]

Technical Skills _____

Languages C/C++, Matlab, Python, Shell

Tools VSCode, Matlab, Jupyter Notebook

Other Git, Latex, Linux

Transferable Skills _____

Creativity Classical music and Literature is for me a source of great inspiration

Teamwork Worked on joint projects during BSc and MSc. Distributing workloads and reaching a compromise in the completion of tasks.

<u>Certified</u> Leisure Time Monitor. Volunteering for the past 7 years in summer camps as organizer. Instructor

Leadership and group leader.